

# Introduction to Elliptic PDEs

Part I.

for online PDE coffee chat

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Agenda We'll talk about the "Dirichlet Problem" for

- ① Laplace Equation
- ② Poisson's Equation

• What is ellipticity?

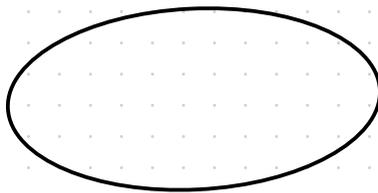
Suppose one is given matrix  $A = (a_{ij})$ . What does  $\{x \in \mathbb{R}^n \mid x^T A x = 1\}$  look like in  $\mathbb{R}^n$ ?

since  $x^T A x = x^T (\frac{1}{2}(A + A^T)) x$  it suffices to consider for  $A$  symmetric.

Say  $n=2$ .  $(x, y) \begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = ax^2 + 2bxy + cy^2 = 1$

if  $\det(A) = ac - b^2 > 0$

then



this is your set.  
↙

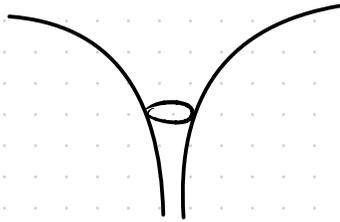
- In general, ellipticity refers to positivity of the leading order coefficient matrix  $A = (a_{ij})$

- Simplest Example is  $\Delta u = 0$  - Laplace Equation

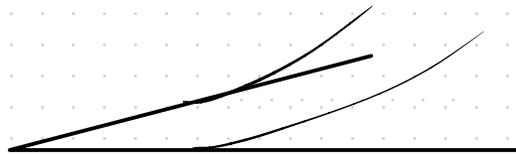
What are some solutions?

- any linear functions
- fundamental solution

$$\bar{T}(x) = \begin{cases} c_n |x|^{2-n} & n \geq 3 \\ c_n \log |x| & n = 2 \end{cases}$$



- cone solutions



they're radial global solutions to  $\Delta \bar{T} = 0$  except at 0.  
 obtained by solving  $\frac{\partial^2}{\partial r^2} u + \frac{n-1}{r} \frac{\partial}{\partial r} u + \frac{1}{r^2} \Delta_{S^{n-1}} u = 0$   
 and assuming for  $u(x) = \bar{T}(x)$ .

$$\begin{aligned} f(r, \theta) &= r^\alpha \cos(\alpha \theta) \quad -\frac{\pi}{2} \leq \alpha \theta \leq \frac{\pi}{2} \\ &= \operatorname{Re}(z^\alpha) \end{aligned}$$

# Some Key Properties for $u \in C^2(\Omega)$ to $\Delta u = 0$ .

① mean value property  $u(x) = \int_{B_r(x)} u \, dy = \int_{\partial B_r(x)} u \, d\hat{\tau}(y)$

this is "iff" for harmonic functions.

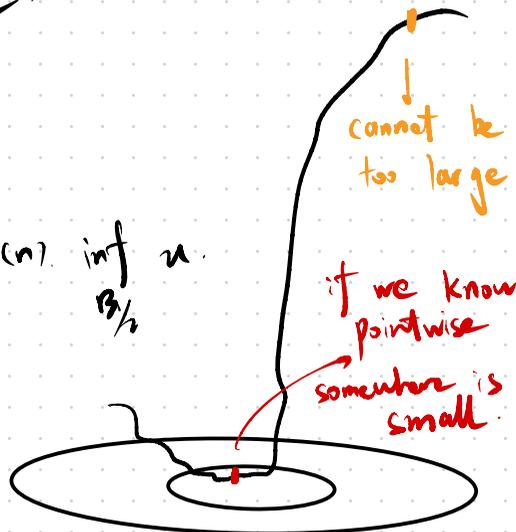
too good to wish for  
for general elliptic PDEs.

② Maximum Principle

$$\begin{cases} \Delta u \geq 0 & \Omega \text{ bounded} \\ u \leq 0 & \partial\Omega \end{cases} \Rightarrow u \leq 0 \text{ in } \Omega$$

③ Harnack Inequality

$$\begin{cases} \Delta u = 0 & B_1 \\ u > 0 & B_1 \end{cases} \Rightarrow \sup_{B_{1/2}} u \leq C \inf_{B_{1/2}} u$$



# A Quick Proof for Maximum Principle without MVP.

$$\begin{cases} \Delta u \geq 0 & B_1 \\ u \leq 0 & \partial B_1 \end{cases} \Rightarrow u \leq 0 \quad B_1$$

Proof

assume at some  $0 \in B_1$ ,  $u(0) > 0$ . the construct a family of barriers

$$\phi_t(x) = t(1 - |x|^2). \quad \text{note } \Delta \phi_t = -2nt < 0$$

since  $\phi_t \geq u$  on  $\partial B_1$

at some  $t_0 > 0$ .

$$\begin{cases} \phi_{t_0}(0) = u(0) \\ \phi_{t_0} \geq u & B_1 \end{cases}$$

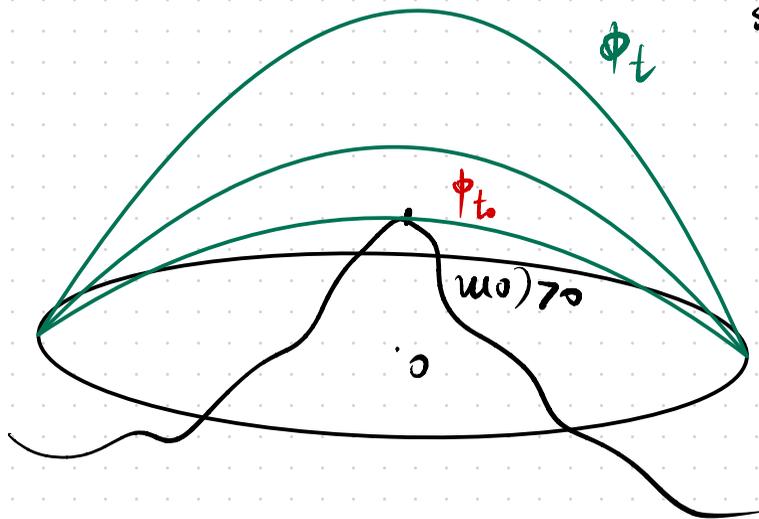
$\Rightarrow \phi_{t_0} - u$  has interior local minimum.

$$\Rightarrow \Delta(\phi_{t_0} - u) \geq 0$$

$$\text{But } 0 \leq \Delta u \leq \Delta \phi_{t_0} = -2nt_0 < 0$$

Contradiction!

□



• In this talk we study Dirichlet Problem which asks the following

- Given an equation
- Given a region where this equation is satisfied
- Given Boundary Data

⇒

① Existence & Uniqueness

Can I "solve" the equation?

If so, "solve" in what sense? Is the solution unique?

② Interior Regularity

How "smooth" can my solution become in the interior?

③ Boundary Regularity

If my boundary data is sufficiently smooth, can my solution approach the boundary data as smooth?

Or even more

④ Higher Regularity

If my coefficients, domain and boundary data are "smooth enough",  
Does my solution inherit the smoothness?

⑤ If I cannot solve the problem.

Can I say something about when this happens?

# Problem ①

Dirichlet Problem for  $\Delta u = 0$  on Balls.

$$\begin{cases} \Delta u = 0 & B_1 \\ u = g & \partial B_1 \end{cases}$$

## Method to solve

Poisson's Integral formula.  $u(x) = (1 - |x|^2) \int_{\partial B_1} \frac{g(y)}{|x-y|^n} dH^{n-1}(y)$

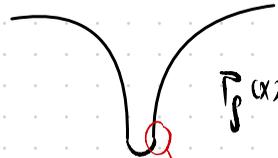
A formal derivation: for  $u, v$  smooth,  $\Omega$  nice.

$$\int_{\Omega} \Delta u \cdot v = - \int_{\Omega} \nabla u \cdot \nabla v + \int_{\partial \Omega} \frac{\partial u}{\partial \nu} v \, dS$$

assume  $\Delta u = 0 \Rightarrow \int_{\Omega} u \Delta v + \int_{\partial \Omega} \frac{\partial u}{\partial \nu} v \, dS - \int_{\partial \Omega} u \frac{\partial v}{\partial \nu} \, dS$

Choose  $v = P_f$  let  $f \rightarrow 0$ .

$$\rightarrow 0 = \int_{\Omega} u \Delta P + \int_{\partial \Omega} \frac{\partial u}{\partial \nu} P \, dS - \int_{\partial \Omega} u \frac{\partial P}{\partial \nu} \, dS$$



$$P_f(x) = \begin{cases} P(x) & |x| \geq f \\ C^2 \text{ polynomial} & |x| < f \end{cases} \Rightarrow \text{with } P \text{ pole centered at } x_0 \in \Omega.$$

designed so  $\Delta P_f = \frac{1}{|B_f|} \chi_{B_f}$  this recovers  $\Rightarrow \Delta P_f \rightarrow \delta_0$  as  $f \rightarrow 0$ .

$$u(x_0) = \int_{\partial \Omega} u \frac{\partial P}{\partial \nu} \Big|_{x_0} \, dS - \int_{\partial \Omega} \frac{\partial u}{\partial \nu} P \Big|_{x_0} \, dS \quad (*)$$

But we want to solve the "Dirichlet problem".

we know  $u|_{\partial\Omega}$  But not  $\frac{\partial u}{\partial \nu}|_{\partial\Omega}$

Can I redesign and get rid of this?

YES! we introduce **Green's function**  $G_{x_0}(y) := P_{x_0}(y) + h_{x_0}(y)$

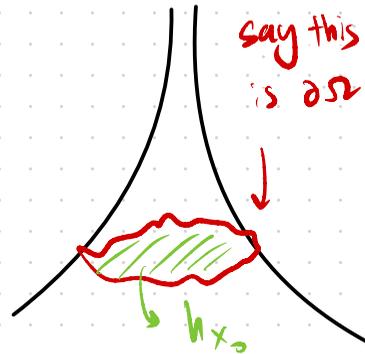
where  $h_{x_0}$  is harmonic replacement

If such " $h_{x_0}$ " exists for  $\Omega$

then (\*) writes

$$\begin{cases} \Delta h_{x_0} = 0 & \text{in } \Omega \\ h_{x_0} = -P_{x_0} & \text{on } \partial\Omega \end{cases}$$

$$u(x_0) = \int_{\partial\Omega} u(y) \frac{\partial G_{x_0}(y)}{\partial \nu}(y) dS(y) \quad \text{Green's Representation}$$

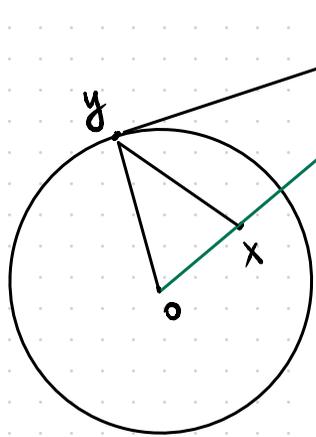


Good News! for  $\Omega = B_1$  one is able to find  $h_{x_0}$ !

How? By reflecting the pole outside  $B_1$ .

We ask How to construct a harmonic function in  $B_1$  that has boundary data  $-P_{x_0}$  on  $\partial B_1$ ?

$x^* := \frac{x}{|x|^2}$  reflect so that Recall  $\bar{T}_{x_0} = C_n |y - x_0|^{2-n}$



$$\Delta y_0 x \simeq \Delta x^* o y$$

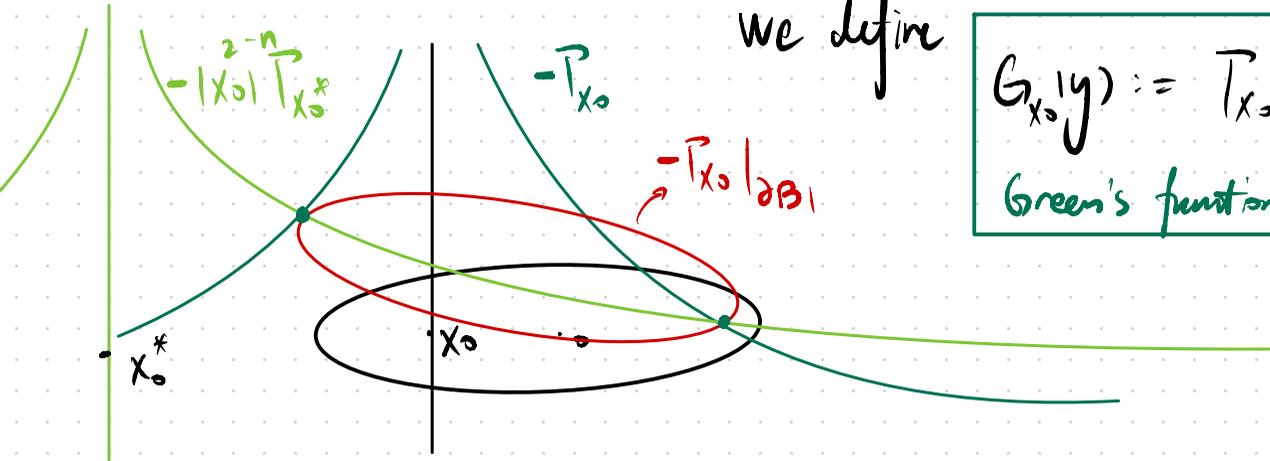
i.e.,  $\frac{|x^* y|}{1} = \frac{|y - x|}{|x|} \quad \forall y \in \partial B_1$

Now design  $h_{x_0} := -|x_0|^{2-n} \bar{T}_{x_0^*}(y)$

We define

$$G_{x_0}(y) := \bar{T}_{x_0}(y) - |x_0|^{2-n} \bar{T}_{x_0^*}(y)$$

Green's function for  $B_1$



look at the Green's Kernel  $\Delta(y) = \frac{1}{|y|}$  outwards normal on  $B_1$

$$\frac{\partial G}{\partial \nu_y} x_0(y) = \frac{1}{n \omega_n} \frac{1 - |x_0|^2}{|x_0 - y|^n}$$

Hence we construct Poisson's Integral formula  $u(x_0) = (1 - |x_0|^2) \int_{\partial B_1} \frac{g(y)}{|x_0 - y|^n} d\mu^{n-1}(y)$

Interior Regularity Can we differentiate in  $x_0$ ?

even in general, yes! can check that  $G_{x_0}(y) = G_y(x_0)$

thus for any  $y \in \partial B_1$ ,  $\Delta_{x_0} G_y(x_0) = 0$

thus using Dominated Convergence theorem.

$$\Delta u(x_0) = 0 \quad \forall x_0 \in B_1$$

$\Rightarrow$  By mean value property we know  $u \in C^\infty(B_1)$

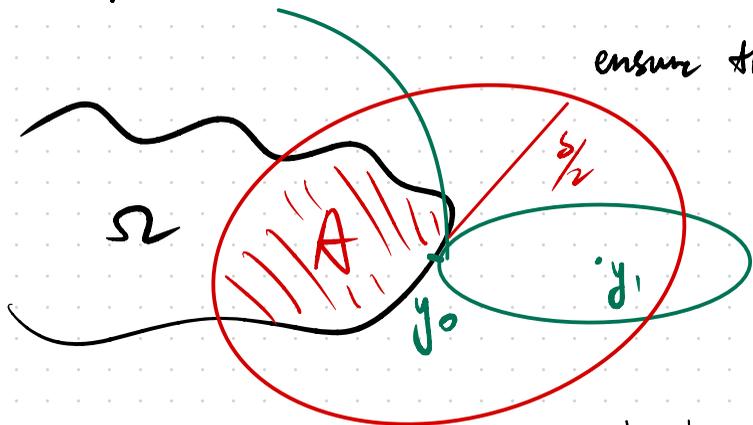
Green's function is symmetric.

# Continuously Approach Boundary Data

Assume  $g \in C(\partial\Omega)$

Can I show that  $u(x) = \int_{\partial\Omega} g(y) \frac{\partial G}{\partial \nu}(x|y) d\mu^{n-1}(y)$  continuously approach  $g$ ?

If  $\partial\Omega$  has exterior Ball condition, then yes!



ensure that  $\forall \delta > 0, \sup_{|y-y_0| \geq \delta} \frac{\partial G}{\partial \nu}(x) \xrightarrow{x \rightarrow y_0} 0$

One may design Barrier  $w_{y_1}$  that satisfies

$$\begin{cases} \Delta w_{y_1} \leq 0 & \text{A} \\ w_{y_1}(y_0) = 0 \\ w_{y_1} \rightarrow \infty & \text{A} \end{cases}$$

$$A = B_{\frac{r}{2}}(y_0) \cap \Omega$$

to trap boundary data  $\frac{\partial G}{\partial \nu}(x) \leq w_{y_1}(x) \quad \forall x \in \partial A$

Now since  $\frac{\partial G}{\partial \nu}$  is harmonic and  $w_{y_1}$  is super harmonic

$\Rightarrow$  By Maximum Principle

$\forall |y-y_0| \geq \delta, y_0 \in \partial B_1$

$$\sup_{|y-y_0| \geq \delta} \frac{\partial G}{\partial \nu}(x) \leq w_{y_1}(x) \quad \forall x \in A$$

send  $x \rightarrow y_0$ .

Why bother doing the above? use  $\int_{\partial\Omega} \frac{\partial G}{\partial \nu} \times \nu \, dS(y) = 1$

$$|u(x) - g(x_0)| = \left| \int_{\partial\Omega} (g(x) - g(x_0)) \frac{\partial G}{\partial \nu} \times \nu \, dS(y) \right|$$

$$\leq \int_{|y-x_0| \leq \delta} |g(x) - g(x_0)| \left| \frac{\partial G}{\partial \nu} \right| + \int_{|y-x_0| > \delta} |g(x) - g(x_0)| \left| \frac{\partial G}{\partial \nu} \right|$$

$\downarrow$   $\% g \in C(\partial B_1)$

$\downarrow$   
due to uniform convergence  
outside  $\delta$ -neighborhood.

$\Rightarrow \rightarrow 0$  as  $x \rightarrow x_0$ .

Thus we conclude  $u \in C^\infty(B_1) \cap C^0(\bar{B}_1)$

Uniqueness

Do I have uniqueness?

Yes. By  $B_1$  is hdd domain & maximum principle

# Problem ②

Dirichlet Problem for  $\Delta u = 0$  on  $\Omega$   
with exterior Ball condition

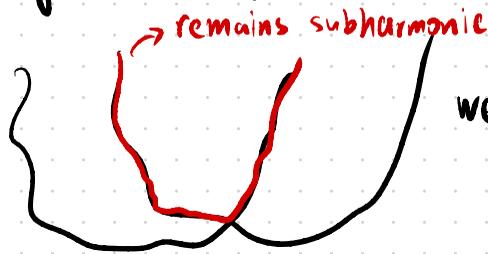
$$\begin{cases} \Delta u = 0 & \Omega \\ u = g & \partial\Omega \end{cases}$$

for example,  $\Omega \in C^2$  has exterior ball condition.

Method to solve

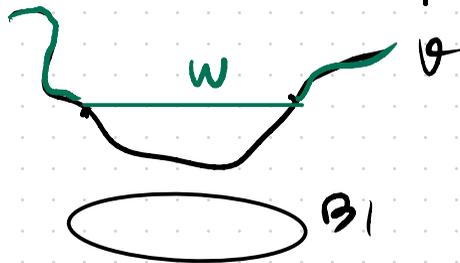
$$\text{Perron's Method } u(x) := \sup \left\{ v(x) \mid \begin{array}{l} v \leq g \text{ on } \partial\Omega \\ v \text{ subharmonic in } \Omega \\ v \in C(\bar{\Omega}) \end{array} \right\}$$

key important fact: subharmonic functions remain subharmonic upon taking maximum.



we also define harmonic lifting  $W$  for any  $v$  s.t.  $\Delta v \geq 0$ .

$$\text{as } \begin{cases} \Delta W = 0 & B_1 \\ W = v & \partial B_1 \end{cases} \rightarrow \text{this is solvable due to our Problem ①}$$



use MVP one can see  $v \leq W$  in  $B_1$   
thus  $\max\{u, v\}$  over  $\Omega \supseteq B_1$   
remains subharmonic function.

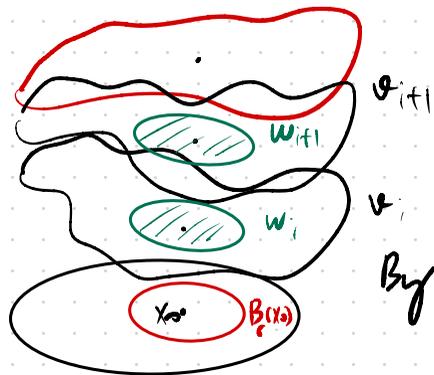
Claim  $u(x)$  is harmonic in  $\Omega \Rightarrow u \in C(\bar{\Omega})$  interior regularity these constants are subharmonic

first of all, the admissible set is nonempty because  $m := \inf_{\Omega} g \leq v \leq M := \sup_{\Omega} g$

Due to definition via "sup" one may take "maximizing sequence" to  $u$ .

Pick any  $x_0 \in \Omega$  and  $B_r(x_0) \subset \Omega$ . Choose  $\{v_i\}$  admissible s.t.  $\lim_{i \rightarrow \infty} v_i(x_0) = u(x_0)$

take  $\{w_i\}$  as harmonic lifting of  $v_i$  in  $B_r(x_0)$



then  $\{w_i\}$  remains "admissible"

moreover

$$\left. \begin{aligned} m \leq v_i \leq w_i \leq u & \quad B_r(x_0) \\ \lim_{i \rightarrow \infty} v_i(x_0) = \lim_{i \rightarrow \infty} w_i(x_0) = u(x_0) & \\ \Delta w_i = 0 & \quad B_r(x_0) \end{aligned} \right\}$$

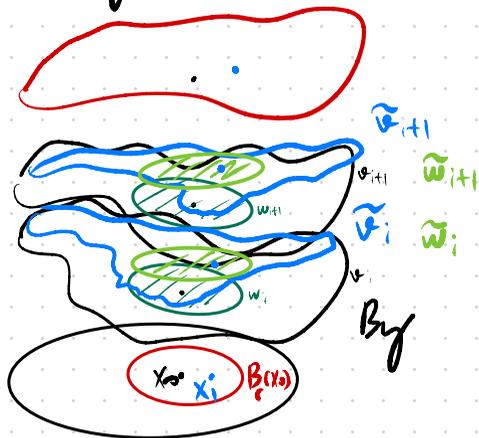
By uniform convergence of harmonic functions preserve "harmonicity"

and, by  $W_{2,1}$ -Arzela interior gradient estimate we know  $W := \lim_{i \rightarrow \infty} w_i$  remains harmonic in  $B_r(x_0)$  up to subsequences

But we only know  $W(x_0) = u(x_0)$  at this single point.

If we know  $W = u$  in  $B_r(x_0)$  we're happy

To see this, take another point  $x_1 \in B_r(x_0)$ ,  $x_1 \neq x_0$ .



Repeat the same procedure as above just this time, take "maximizing sequence"

$$\{\tilde{v}_i\} \text{ s.t. } \tilde{v}_i \geq w, \quad \forall i$$

then take  $\{\tilde{w}_i\}$  harmonic lifting of  $\tilde{v}_i$  in  $B_r(x_0)$

$$m \leq v_i \leq w_i \leq \tilde{v}_i \leq \tilde{w}_i \leq u$$

$$\lim_{i \rightarrow \infty} \tilde{v}_i(x_1) = \lim_{i \rightarrow \infty} \tilde{w}_i(x_1) = u(x_1)$$

$$\lim_{i \rightarrow \infty} \tilde{v}_i(x_0) = \lim_{i \rightarrow \infty} \tilde{w}_i(x_0) = \tilde{w}(x_0) = w(x_0) = u(x_0)$$

By Ascoli-Arzelà,  $\tilde{w} := \lim_{i \rightarrow \infty} \tilde{w}_i$  is another harmonic function in  $B_r(x_0)$

$$\text{But } \begin{cases} \Delta \tilde{w} = \Delta w = 0 & B_r(x_0) \\ \tilde{w}(x_0) = w(x_0) \end{cases}$$

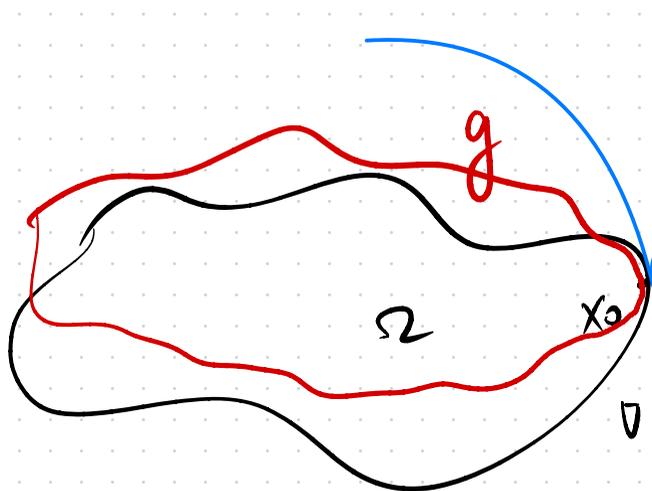
By **Strong Maximum Principle** we know  $\tilde{w} = w$  in  $B_r(x_0)$

In particular at  $x_1$ ,  $u(x_1) = \tilde{w}(x_1) = w(x_1)$ . But  $x_1$  is arbitrary  $\square$

# Continuously Approach Boundary Data

let  $g \in C(\partial\Omega)$

Can we show that  $u$  continuously approach Boundary Data  $g$ ?



Barrier  $w_{x_0}(y) := \Gamma_{y_0}(y) - \underbrace{\Gamma_{y_0}(x_0 - y_0)}_{\text{constant}}$

so that

$$\begin{cases} \Delta w_{x_0}(x) \leq 0 & \Omega \\ w_{x_0}(x_0) = 0 \\ w_{x_0} \geq 0 & \Omega \end{cases}$$

$$\forall \varepsilon > 0, \exists \delta > 0 \text{ s.t. } |g(y) - g(x_0)| < \varepsilon \quad \forall |y - x_0| < \delta$$

if on the other hand  $|y - x_0| \geq \delta$ ,  $|g(y) - g(x_0)| \leq 2 \sup_{\partial\Omega} |g| = K w_{x_0}(y)$  this does not degenerate because  $|y - x_0| \geq \delta$

$$\Rightarrow -\varepsilon - K w_{x_0}(y) \leq g(y) - g(x_0) \leq \varepsilon + K w_{x_0}(y)$$

$$\forall y \in \partial B_\delta$$

large enough

Our goal is to replace the above  $g(y)$  with  $u(y)$ , and for  $y \in \Omega$

→ 
$$-\varepsilon - K W_{x_0}(y) + g(x_0) \leq u(y) \quad \forall y \in \Omega$$
  
this is subharmonic function below boundary data → using construction of  $u$  via Perron's method.

→ on the other hand,

$$v(y) \leq g(y) \leq g(x_0) + \varepsilon + K W_{x_0}(y) \quad \forall y \in \partial \Omega$$

this is superharmonic

$v$  is admissible subharmonic.

By **Maximum Principle**

$$v(y) \leq g(x_0) + \varepsilon + K W_{x_0}(y) \quad \forall y \in \Omega$$

But  $v$  is arbitrary admissible subharmonic function.  
take sup gives  $u$ .

→  $|u(y) - g(x_0)| \leq \varepsilon + K W_{x_0}(y)$ . first send  $y \rightarrow x_0$ , then  $\varepsilon \downarrow 0$ .  
we conclude  $u \in C^{\alpha}(\Omega) \cap C^0(\bar{\Omega})$  □

Problem ③ Dirichlet problem for  $\Delta u = f$  Poisson's Equation

$$\begin{cases} \Delta u = f & \Omega \\ u = g & \partial\Omega \end{cases} \quad \text{with } \Omega \text{ exterior Ball condition.}$$

What conditions on  $f$  can we make this problem well-posed?

morally, one want to decompose  $u = v + w$ .

where  $\Delta w = f$   $\mathbb{R}^n$ ,  
for  $f$  compactly supported.

$$\begin{cases} \Delta v = 0 & \Omega \\ v = u - w & \partial\Omega \end{cases}$$

this has unique solution  
from our Problem ②

It suffices to study the behavior of  
 $w$  s.t.  $\Delta w = f$ .

• Define **Newtonian Potential**  $u(x) := \int_{\mathbb{R}^n} f(y) \tilde{P}(x-y) dy$

Why is this a reasonable choice?

Recall our derivation

$$\int_{\Omega} \Delta u \tilde{P} = \int_{\Omega} u \Delta \tilde{P}_{x_0} + \int_{\partial\Omega} \frac{\partial u}{\partial \nu} \tilde{P}_{x_0} ds - \int_{\partial\Omega} u \frac{\partial \tilde{P}}{\partial \nu} ds$$

$$\int_{\Omega} \underbrace{\Delta u}_{f''} \underbrace{\tilde{G}_{x_0}}_{\tilde{G}_{x_0}} = \int_{\Omega} u \underbrace{\Delta \tilde{G}_{x_0}}_{\delta_{x_0}} - \int_{\partial\Omega} u \frac{\partial \tilde{G}_{x_0}}{\partial \nu} ds$$

Also recall

$$\tilde{G}_{x_0} = \tilde{P}_{x_0} + \underbrace{h_{x_0}}_{\text{harmonic in } \Omega}$$

thus  $u(x_0) = \underbrace{\int_{\Omega} f(y) \tilde{P}(x_0-y) dy}_{\text{Newtonian Potential}} + \text{something harmonic}$

we take Newtonian Potential from here.

When is this well-defined? Recall  $P(x) = C_n |x|^{2-n}$

→ When is  $w \in C^0$ ? let  $\text{supp}(f) \subseteq B_R$ .

$$|w(x)| \leq \int_{B_R} |f| |P| \approx \|f\|_{L^p} \int_0^R r^{(2-n)p'} r^{n-1} dr$$

where  $p' = \frac{p}{p-1}$  need  $(2-n)\frac{p}{p-1} + n-1 > -1$

$$p > n/2$$

→ When is  $w \in C^1$ ?

$$|Dw(x)| \leq \int_{B_R} |f| |DP| \approx \|f\|_{L^p} \int_0^R r^{(1-n)p'} r^{n-1} dr$$

need  $(1-n)\frac{p}{p-1} + n-1 > -1$

$$p > n$$

But can we repeat the same procedure for  $w \in C^2$ ? No!

For  $w$  to be  $C^2$  we in fact need  $f \in C_0^{\alpha}$  compact support for  $0 < \alpha < 1$

Formula

$$\partial_j w(x) = \frac{\delta_{ij}}{n!} f(x) + \text{p.v.} ( \partial_j T * f ) (x) \quad (*)$$

where  $\text{p.v.} (K * f)(x) := \lim_{\varepsilon \rightarrow 0} \int_{B_\varepsilon(x)} K(y) f(x-y) dy$  for some kernel  $K$ .

→ We can develop some theory for  $K: \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}$  that is

- homogeneous of degree  $-n$ , i.e.,  $K(x) = |x|^{-n} g(\frac{x}{|x|})$
- $\int_{\partial B_1} K dS_y = 0$

assume  $g: \partial B_1 \rightarrow \mathbb{R}$   
Lipschitz

Indeed  $\partial_j T$  satisfies such requirements for  $K$ .

→ Claim: for  $f \in C_0^\alpha$ ,  $Tf(x) := \text{p.v.} (K * f)(x)$  is continuous

proof notice  $\int_{\mathbb{R}^n \setminus B_\varepsilon} K = \int_{\mathbb{R}^n} s^{-n} \cdot s^{n-1} \int_{\partial B_s} g dH^{n-1} ds = 0$

thus  $\forall \varepsilon > 0$ ,  $\int_{\mathbb{R}^n \setminus B_\varepsilon} f(x-y) K(y) dy = \int_{\mathbb{R}^n \setminus B_\varepsilon} (f(x-y) - f(x)) K(y) dy \leq C f_0 \int_{\mathbb{R}^n} r^{-\alpha-n} r^{n-1} dr < \infty$  uniformly in  $\varepsilon$

thus  $\|Tf\|_\infty \leq C$

moreover  $\int_{B_\varepsilon(x)} (f(x-y) - f(x)) K(y) dy \leq C f_0 \int_0^\varepsilon r^{-\alpha-n+n-1} dr \leq C f_0 \varepsilon^\alpha \rightarrow 0$   
 $\Rightarrow Tf$  is continuous □

→ We show the formula (\*)

Proof take  $T_\varepsilon$  as our approximation for  $T$

$$\begin{aligned} \text{then } \partial_j w^\varepsilon &= \partial_j (T_\varepsilon^* f) = (\partial_j T_\varepsilon)^* f = (\partial_j T^\varepsilon \chi_{B_\varepsilon})^* f + (\partial_j \tilde{T}_{B_\varepsilon^c}^\varepsilon)^* f \\ &= \left( \frac{\sum_j}{n |B_\varepsilon|} \chi_{B_\varepsilon} \right)^* f + (\partial_j \tilde{T}_{B_\varepsilon^c}^\varepsilon)^* f \\ &\xrightarrow{\varepsilon \rightarrow 0} \frac{\sum_j}{n} f(x) + \text{p.v.} ( \partial_j T^* f ) (x) \quad \square \end{aligned}$$

We've demonstrated that

$$\text{for } f \in C^{0,\alpha} \Rightarrow w \in C^2$$

therefore our problem (3) admits  $u \in C^2(\Omega) \cap C^0(\bar{\Omega})$  solution

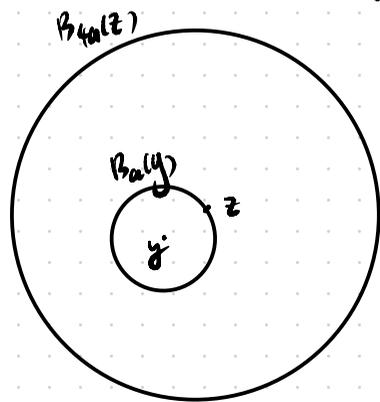
**BUT**

since  $f \in C^{0,\alpha}$ , why can't  $u \in C^{2,\alpha}(\Omega)$  ???

let's check this!

→ Claim: for  $f \in C^{0,\alpha}$  in fact  $Tf(x) \in C^{0,\alpha} \Rightarrow u \in C^{2,\alpha}(\Omega) \cap C^0(\bar{\Omega})$

Proof take arbitrary  $y \neq z$ . denote  $a = |y - z|$



$$\begin{aligned} \text{then } Tf(z) &= \int_{\mathbb{R}^n} K(z-x) (f(x) - f(z)) dx \\ &= \underbrace{\int_{B_{4a}(z)} \dots}_{o(a^\alpha)} + \int_{B_{4a}(z)}^c K(z-x) (f(x) - f(z)) dx \end{aligned}$$

$$Tf(y) = \int_{\mathbb{R}^n} K(y-x) (f(x) - f(y)) dx$$

$$= \underbrace{\int_{B_a(y)} \dots}_{o(a^\alpha)} + \int_{B_{4a}(z) \setminus B_a(y)} K(y-x) (f(x) - f(z)) dx + \int_{B_{4a}(z)}^c K(y-x) (f(x) - f(z)) dx$$

free to switch since away from  $y$

Now subtract both.

$$|Tf(y) - Tf(z)| \leq \int_{B_{4a}(z)}^c |K(z-x) - K(y-x)| |f(x) - f(z)| dx$$

$$\lesssim \int_{C^0} \cdot a \cdot \int_{4a}^\infty r^{-(n+1)} \cdot r^\alpha \cdot r^{n-1} dr = o(a^\alpha)$$

$\Rightarrow Tf \in C^{0,\alpha}$



$o(a^\alpha)$  using the ball  $B_{4a}(z)$